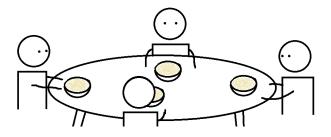
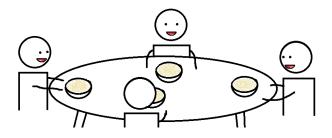
Synthesizing strategies to avoid deadlocks

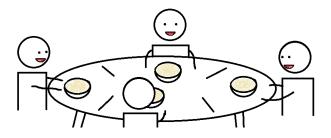
Corto Mascle

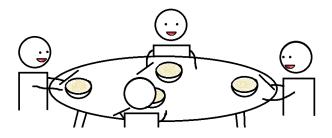
Joint work with Hugo Gimbert, Anca Muscholl and Igor Walukiewicz

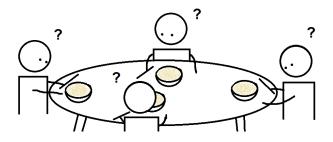
RP 2022

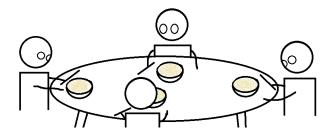


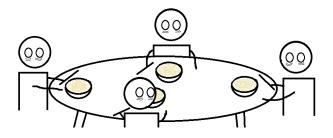


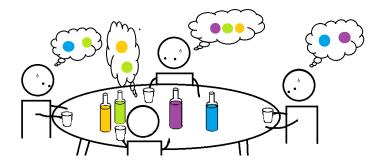










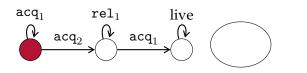


Lock-sharing systems (LSS)

Lock-sharing systemProc: set of processesT: set of locks .

Lock-sharing system: $\mathcal{A}_p = (S_p, \Sigma_p, \delta_p, init_p)$ for each $p \in Proc$.

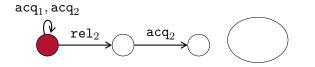
Transitions include operations on locks : $\delta_p: S_p \times \Sigma_p \to Op_T \times S_p$ with $Op_T = \{acq_t, rel_t \mid t \in T\} \cup \{nop\}.$

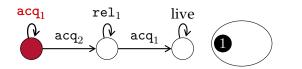


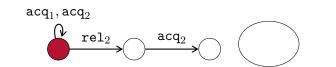
0 2

 p_1

 p_2

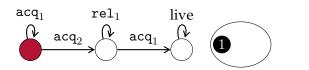


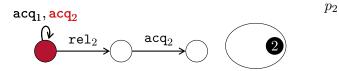




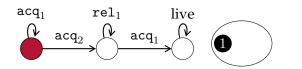
 p_2

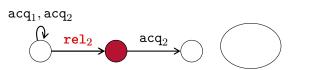
 p_1





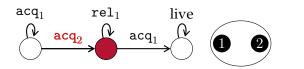
 p_1



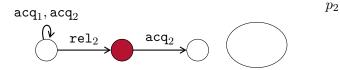


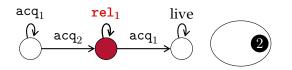
 p_1

 p_2



 p_1

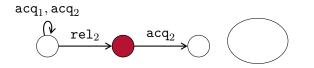


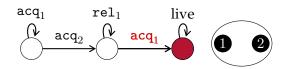




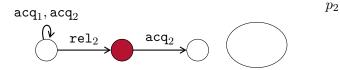
 p_2

1





 p_1

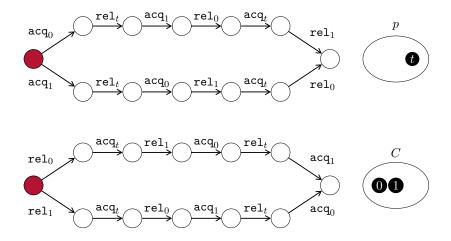


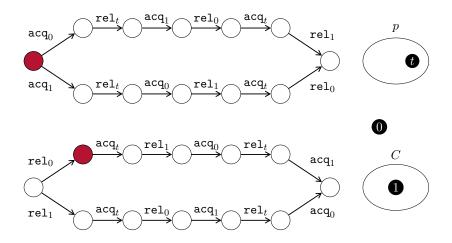
A problem

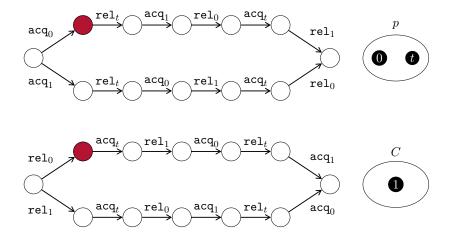
Model-checking problem

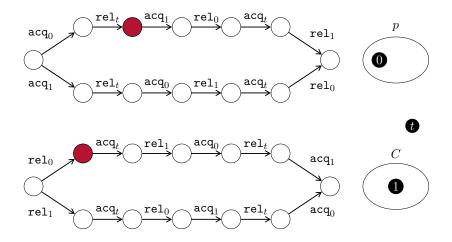
Input: A set of processes *Proc*, a set of locks *T*, an LSS $(\mathcal{A}_p)_{p \in Proc}$, a property \mathcal{P} (for instance $\mathcal{P} =$ "the run ends in a deadlock")

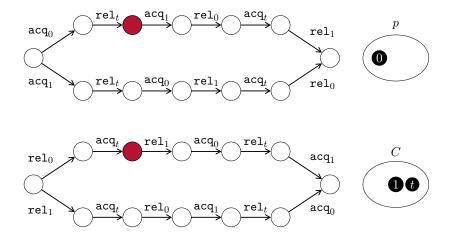
Output: Is there a run satisfying \mathcal{P} ?

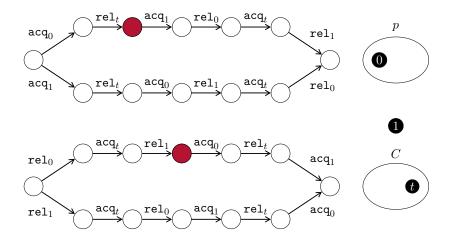


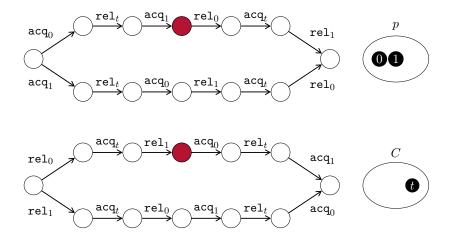


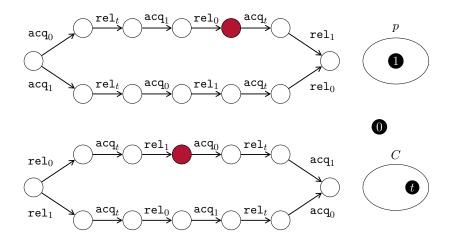


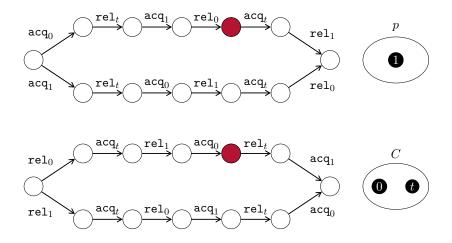


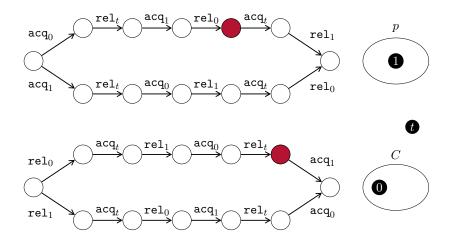


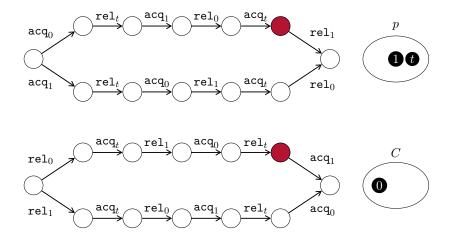


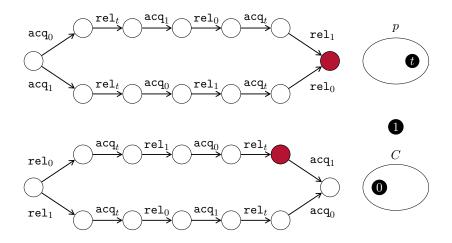


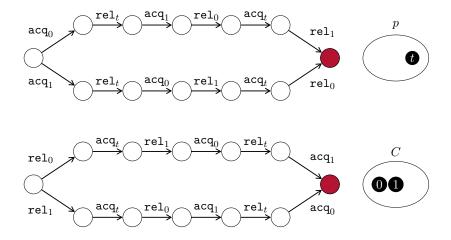












If we can pass unlimited information, **PSPACE-complete**

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2LSS

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Nested LSS

All processes acquire and release locks in a **stack-like order**, i.e., a process can only release the lock it acquired the latest.

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2LSS

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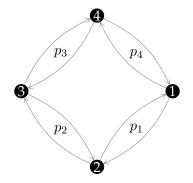
Nested LSS

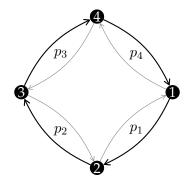
All processes acquire and release locks in a **stack-like order**, i.e., a process can only release the lock it acquired the latest. Those cases are generally **NP-complete**



We summarize runs as short patterns.

Patterns tell us if some local runs can be interleaved into a global run leading to a deadlock.





Synthesis

Processes can forbid some transitions $think_i$ $left_i$ acq_{cs_i} $acq_{cs_{i+1}}$ $right_i$ $acq_{cs_{i+1}}$ acq_{cs_i} rel_{cs_i} , $rel_{cs_{i+1}}$

If σ_{p_i} always selects $left_i$ and σ_{p_j} $right_j$ for some processes $i \neq j$ then it avoids deadlocks.

Strategies

System and Environment actions $\Sigma_p = \Sigma_p^s \sqcup \Sigma_p^e$. Strategy $(\sigma_p)_{p \in Proc}$ with $\sigma_p : \Sigma_p^* \to 2^{\Sigma_p}$ such that $\Sigma_p^e \subseteq \sigma_p(u)$ for all u.

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Locally live strategy

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Locally live strategy

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Global deadlock

A σ -run u reaches a *global deadlock* if all processes are blocked at the end.

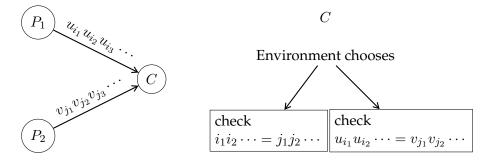
Undecidability

Theorem

The existence of a strategy avoiding global deadlocks is undecidable, even with 3 processes and 4 locks in total.

Proof scheme: PCP encoding

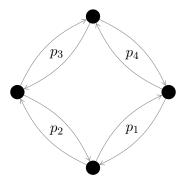
Let $(u_1, v_1), \ldots, (u_n, v_n)$ be a PCP instance.



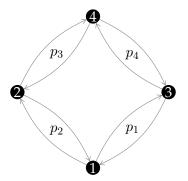
Decidability

Theorem

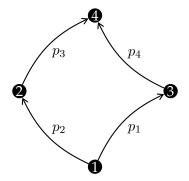
The existence of a strategy avoiding global deadlocks is Σ_2^P -complete for 2LSS and NEXPTIME-complete for LSS respecting the nested lock condition.



 \rightarrow Just pick an order on chopsticks and have all philosophers take them accordingly!

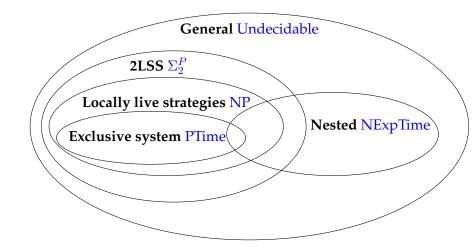


 \rightarrow Just pick an order on chopsticks and have all philosophers take them accordingly!



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Results



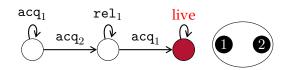
An open problem

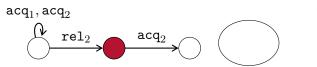
Can the following problem be solved in PTIME ?

Mortality problem

Input: A 2LSS (each process uses at most 2 locks). **Output:** Is there a run such that one of the processes cannot execute any action ever from some point on?

Example





 p_1

 p_2

Thank you for your attention!